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# Advanced Spatial Nonparametric Techniques - Spatial Dependence -

Margherita Gerolimetto and Stefano Magrini

Department of Economics - Ca'Foscari University of Venice

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Spatial autocorrelation (or dependence):

- ▶ one of the most important concepts in spatial statistics and spatial econometrics
- ▶ derived directly from Tobler's first law of geography according to which everything is related to everything else, but near things are more related than distant things (Tobler, 1979)

in particular:

- ▶ positive spatial autocorrelation: similar values tend to group in physical proximity
- ▶ negative spatial autocorrelation: dissimilar values tend to group in physical proximity
- ▶ absence of spatial autocorrelation (or independence): values are randomly distributed across space

- ▶ spatial **autocorrelation/dependence** systematic pattern in the spatial distribution of a variable → it does have severe implications for the empirical analysis!!!!
  - ▶ an observation is partly predictable from neighbouring observations; hence, a series of spatially dependent observations contains less information
  - ▶ implications are more complex to deal with than in time series

So, spatial dependence means that the observations at location  $i$  depend on other observations at locations  $i \neq j$

$$y_i = f(y_j) \quad i \neq j$$

Possible reasons for this:

- ▶ **substantive** spatial dependence due to spatial interactions effects across units (e.g. trade flows, migration, knowledge flows...)
- ▶ **nuisance** spatial dependence, due to measurement errors or wrongly defined spatial units

## Measuring spatial autocorrelation

- ▶ Global measures measure autocorrelation in the whole set of locations
- ▶ local measures measure autocorrelation in a spatially delimited subset of locations

As for global autocorrelation, the most commonly used is the **Moran's I** statistic (Moran, 1948)

$$I = \frac{N}{\sum_i \sum_j w_{ij}} \frac{\sum_i \sum_j w_{ij} (X_i - \bar{X})(X_j - \bar{X})}{\sum_i (X_i - \bar{X})^2}$$

where  $N$  is the number of observations (i.e., locations),  $X_i, X_j$  is the value of the variable in locations  $i$  and  $j$ ,  $\bar{X}$  is the (cross-sectional) mean value of the variable and  $w_{ij}$  is a **spatial weight** assigned to the relation between location  $i$  and location  $j$ .

In matrix notation,

$$I = \frac{N}{S_0} \frac{Z' W Z}{Z' Z}$$

where  $Z$  is a vector (with  $N$  observations) with the variable  $X$  expressed in deviations from the mean,  $W$  is  $N \times N$  **matrix of spatial weights** (usually row-normalised and  $S_0$  is a scalar given by the sum of all elements of  $W$  (equal to  $N$  when  $W$  is row-normalised))

- ▶ Spatial Lag Model ( $-1 < \rho < 1$ )

$$Y = \rho WY + \beta X + \epsilon$$

- ▶ Spatial Error Model ( $-1 < \lambda < 1$ )

$$Y = \beta X + u$$
$$u = \lambda Wu + \epsilon$$

- ▶ Spatial Cross-regressive

$$Y = \beta_1 X + \beta_2 WX + \epsilon$$

... and so on..

Note that  $W$ , the spatial weights matrix, plays a crucial role and it must be specified in advance.

The choice of  $W$  is a very important part of the specification!

- ▶ **Formal** expression of the autocorrelation: it is based on the specification of a spatial process yielding a certain covariance structure.

This involves choosing carefully  $W$ , the **matrix of spatial weights** (usually row-normalised).

- ▶ spatial weights can be based on the geographic arrangement of the observations or contiguity
- ▶ they also can be based on distance decay (inverse or inverse square distance)
- ▶ **Direct** representation: each covariance between a pair of observations  $i$  and  $j$  is specified as a parametrized function  $f$  of the distances  $d_{ij}$

This involves choosing  $f$  very carefully in order to guarantee that the resulting variance-covariance matrix is positive semidefinite